```cpp
#include <Servo.h>

Servo servo[4][3];

//define servos' ports

const int servo_pin[4][3] = { {2, 3, 4}, {5, 6, 7}, {8, 9, 10}, {11, 12, 13}
};

void setup()

{

  //initialize all servos

  for (int i = 0; i < 4; i++)

  {

    for (int j = 0; j < 3; j++)

    {

      servo[i][j].attach(servo_pin[i][j]);

      delay(20);

    }

  }

}

void loop(void)

{

  for (int i = 0; i < 4; i++)

  {

    for (int j = 0; j < 3; j++)

    {

      servo[i][j].write(90);

      delay(20);

    }

  }

}
```